

Fairmat numerical API introduction (for matlab users)

Revision # 5, updated to Fairmat 1.6.x API

1 New methods from 1.6.1

- Vector.MovingAverage(...)
- Sparse Indexing var a = b[new int[]1,3,7]; b[new int[]1, 5]= new Vector(2);
- Correlation Analysis var m= new Matrix(100,3); var b=m.Correlation();

2 Introduction

The Fairmat API contains a series of classes which deal with numerical algorithm matrices and algebra. This tutorial shows some of the features of the numerical classes and puts a particular emphasis on the similarities and differences with the Matlab language.

This tutorial does not contain the complete list of available methods and operations. For a complete reference of the Fairmat API go to <http://www.fairmat.com/documentation/fairmatapi/namespaces.htm>.

3 Matrix and Vector Classes

The Fairmat API contains Vector and Matrices¹ class, the main difference between Matlab matrices and C# matrices is indexing. Matlab matrix indices are one-based, meaning that indices start with the value one, while C# matrix and array indices are in general zero-based.

In the following sections, operations than can be done with matrices are shown in both implementations.

¹Vector, Matrix and Matrix3 are defined in the assembly DVPLI.dll, namespace DVPLI.

3.1 Matrices initialization

Matlab	C# + Fairmat library
a = zeros(1,2);	var a = new Matrix(1,2);
b = ones(1,2);	var b = Matrix.Ones(1,2);
c = zeros(10);	var c = new Matrix(10);
d = 5*ones(10,20);	var d = 5*Matrix.Ones(10,20);
e = [1, 2, 3, 4];	var e = (Matrix)new double []{1,2,3,4};
f = [1 2 ; 3 4];	var f = (Matrix)new double [,]{ {1,2}, {3,4} };
g= eye(5);	var g = Matrix.Identity(5);
h = [f f ; f f];	var h = new Matrix[[]]{new []{f,f}, new []{f,f}}
i = reshape(e, 2, 2);	var i = e.Reshape(2, 2);
l = sum(f);	var l = f.ColumnSum();

3.2 Popular matrices operations

Matlab	C# + Fairmat library
m = max(f);	m = f.Max();
n = mean(f);	n = f.Means();
o = sum(f(:));	o = f.Sum();
p = mean(f(:));	p = f.Mean();
q = f.^2;	q = Matrix.Pow(f, 2);
q2 = f^2;	q2 = Matrix.PowM(f, 2);
q3 = expm(f);	q3 = Matrix.ExpM(f);
r = sqrt(f);	r = Matrix.Sqrt(f);
s = log(f);	s = Matrix.Log(f);
t = exp(f);	t = Matrix.Exp(f);
u = det(f);	u = f.Determinant();
v = inv(f);	v = f.Inverse();

3.3 Vectors initialization and operations

In a similar way, the vector class easy allows to work on vectors.

Matlab	C# + Fairmat library
a = [1 2];	var a = new Vector(){1, 2};
a = linspace(10,20,200);	var a = Vector.Linspace(10,20,200);
b = sum(a)	double b = a.Sum();
c = cumsum(a)	var c = a.CumSum();
d = a[10:100];	var d = a[Range.New(9,99)];

3.4 Matrices transposition

Matlab	C# + Fairmat library
a = zeros(1,2);	var a = new Matrix(1,2);
a = a';	a = a.T;

3.5 Matrices arithmetics

Matlab	C# + Fairmat library
a = ones(2,1);	var a = Matrix.Ones(2,1);
b = ones(1,2)	var b = Matrix.Ones(1,2);
d = a*b - 3;	var d = a*b - 3;

3.6 Operations on range of indices

One of the point of strength of Fairmat Matrix API is that the classes allows easy access to range of indices or sub-section of the matrices.

Matlab	C# + Fairmat library
a = ones(3,3)	var a = Matrix.Ones(3,3);
b = a(:,1)	var b = a[Range.All, 0];
c = zeros(3,4)	var c = new Matrix(3,4);
c(:,1) = b(2,:)	c[Range.All,0] = b[1,Range.All];
d = zeros(4,4);	var d = new Matrix(4,4);
d(1:2,1:2) = ones(2,2);	d[Range.New(0,1),Range.New(0,1)] = Matrix.Ones(2,2);
e = zeros(10,1);	var e = new Vector(10);
e(1:5) = 10.45;	e[Range.New(0,4)] = (Vector)10.45;

3.7 Algebra

The API provides some basic linear algebra algorithms.

Matlab	C# + Fairmat library
a = ones(3,3)	var a = Matrix.Ones(3,3);
d = det(a);	double d = a.Determinant();
e = chol(a);	var e = a.Cholesky();
f = inv(a);	var f = a.Inverse();

3.8 Linear Regression

Linear regression classes are available in the Assembly DVPLUtils.dll, namespace Fairmat.Statistics.

Matlab	C# + Fairmat library
c=a\b	Vector c = LinearRegression.Solve(a,b);

3.9 Statistics

3.10 Descriptive Statistics

The API provides some basic descriptive statistics.

Matlab	C# + Fairmat library
a = ones(3,3)	var a = Matrix.Ones(3,3);
m = mean(a);	Vector m = a.Mean();
cov = cov(a);	var cov = a.Covariance();
corr = corr(a);	var corr = a.Correlation();

3.11 3-Dimensional Matrices

We provide also a basic 3-dimension matrix.

Matlab	C# + Fairmat library
<code>a = ones(2,3,4)</code>	<code>//a is a 2x3x4 matrix var a = Matrix3.Ones(2,3,4);</code>
<code>b = a(:,:,1)</code>	<code>//two-dim sub matrices var b = a[Range.All, Range.All, 0];</code>
<code>c = a(:,1,:)</code>	<code>var c = a[Range.All, 0, Range.All];</code>
<code>d = a[0,:,:]</code>	<code>var d = a[0, Range.All, Range.All];</code>
<code>e = a(:,1,2)</code>	<code>var e = a[Range.All, 0, 1];</code>

4 Numerical integration

Integration is performed by the class `Fairmat.Math.Integrate` which takes an `IIntegrable` object or an `Integrand` delegate as constructor input. See the example below:

```
//1) Includes the integrand function in a class implementing IIntegrable
public class IntegrandClass: IIntegrable
{
    public double IntegrandFunc(double x)
    {
        return Math.Sin(x)*Math.Pow(x,3);
    }
}
//2) Instance the Integrate class
...
Integrate z= new Integrate(IntegrandClass);

//3) use one of the available integration methods in order to integrate from a
to b
var int1=z.AdaptLobatto(a, b);
var int2=z.Rectangle(a,b,20);
var int2=z.Romberg(a,b)
```

5 Mathematical Programming

The Fairmat library contains also some implementation of optimization algorithms suited for small-size nonlinear mathematical programming problems.²

We provide both an object oriented framework and an imperative (delegate based) framework. In the object oriented version, the mathematical programming problem is defined by a class like in the following example:

```
public class SimpleProblem: IOptimizationProblem
{
```

²The Mathematical programming algorithms are contained in the assembly Fairmat.Optimization.dll, namespace Fairmat.Optimization.



```

public double Obj(DVPLI.Vector x)
{
    return (x - 2.0).Scalar(x - 2.0);
}

//implement (is applicable) analytical gradient
public DVPLI.Vector Grad(DVPLI.Vector x)
{
    throw new NotImplementedException();
}

public Bounds Bounds
{
    get
    {
        Bounds b= new Bounds();
        b.Lb =(Vector) new double[] { 0, 0,0,0,0};
        b.Ub = (Vector)new double[] { 100, 100, 100, 100, 100 };
        return b;
    }
}

//Defines the constraint Ax<=b
public LinearConstraints LinearIneqConstraints
{
    get
    {
        LinearConstraints l = new LinearConstraints();
        Matrix A = new Matrix(1, 5);
        Vector b = new Vector(5);
        A [0, 0] = -1;
        A [0, 1] = +1;
        l.A = A;
        l.b = b;
        return l;
    }
}

public bool HasNonLinearConstraints
{
    get { return false; }
}

//feasible region is defined by x | G(x)<=0
public DVPLI.Vector G(DVPLI.Vector x)
{
    throw new NotImplementedException();
}

```

After the problem is defined you can find the optimal solution in the following way:

```
//Instantiate a Quasi Newton local optimization algorithm
IOptimizationAlgorithm algorithm= new SteepestDescent();

OptimizationSettings settings = new OptimizationSettings();

settings.MaxIter=50; // maximum number of iteration allowed
settings.Verbose = 1; // positive integer values print debug info
settings.epsilon = 10e-4;// tolerance

//optional starting point
Vector x0 = (Vector)new double[] { 10, 30,50,60 };
var solution = algorithm.Minimize(new SimpleProblem(),settings,x0);
Console.WriteLine(solution);
```

In addition we offer a delegate based API which can be used for simpler problems defined only by an objective function:

```
Vector x0 = (Vector)new double[] { 10, 30,50,60 };
var solution = Fairmat.Optimization.Helper.Minimize(new ObjFunc(Func),x0);
Console.WriteLine(solution);
...
double Func(Vector x){
return ...
}
```